



%The above specifications are subject to change and some models may be discontinued without notice %Be sure to follow cautions written in the instruction manual, and the technical descriptions (catalog, homepage).

## Specifications

Item		Side-mounting shaft type of incremental rotary encoder	Wheel type of incremental rotary encoder			
Totem pole output		ENA	ENC-1			
NPN open	collector output	ENA-C	ENC-1			
Voltage output		ENAV	ENC-1			
Resolution(PPR) <sup>×1</sup>		*1, *2, *5, 10, 12, 15, 20, 23, 25, 30, 35, 40, 45, 50, 60, 75, 100, 120, 125, 150, 192, 200, 240, 250, 256, 300, 360, 400, 500, 512, 600, 800, 1000, 1024, 1200, 1500, 1800, 2000, 2048, 2500, 3000, 3600, 5000	1mm/Pulse, 1cm/Pulse, 1m/Pulse, 0.01yd/Pulse, 0.1yd/Pulse, 1yd/Pulse			
Output phase		ENA	A, B phase			
		ENA	A, b phase			
Phase difference of output		Output between A and B phase: $\frac{T}{4} \pm \frac{T}{8}$ (T= 1 cycle of A phase)				
Control	Totem pole output	[Low] - Load current: Max. 30mA, Residual voltage: Max. 0.4VDC= [High] - Load current: Max. 10mA, Output voltage(Power voltage 5VDC=): Min. (Power voltage-2.0)VDC=-, Output voltage(Power voltage 12-24VDC=): Min. (Power voltage-3.0)VDC=				
output	NPN open collector output	Load current: Max. 30mA, Residual voltage: Max. 0.4VDC==				
	Voltage output	Load current: Max. 10mA, Residual voltage: Max. 0.4VDC				
Response	Totem pole output					
time (rise/fall)	NPN open collector output	Max. 1µs (Cable length:2m, I sink = 20mA)				
	Voltage output					
Max. Response frequency		300kHz	180kHz			
Power supply		•5VDC= ±5%(Ripple P-P: Max. 5%) •12-24VDC= ±5%(Ripple P-P: Max. 5%)				
Current consumption		Max. 80mA(disconnection of the load)				
Insulation resistance		Min. 100MΩ(at 500VDC megger between all terminals and case)				
Dielectric strength		750VAC 50/60Hz for 1 minute(Between all termials and case)				
Connection		Radial connector type	Axial cable type, Axial cable connector type			
Starting torque		Max. 70gf·cm(0.007N·m)	Dependent on the coefficient of friction			
Moment of inertia		Max. 80g·cm <sup>2</sup> (8×10 <sup>-6</sup> kg·m <sup>2</sup> )				
Shaft loading		Radial: 10kgf, Thrust: 2.5kgf				
Max. allowable revolution $^{\!\!\!\!\times\!\!\!^2}$		5000rpm				
Vibration		1.5mm amplitude at frequency of 10 to 55Hz(for 1 min.) in each X, Y, Z direction for 2 hours				
Shock		Approx. Max. 75G				
Ambient temperature		-10 to 70°C, Storage: -25 to 85°C				
Ambient humidity		35 to 85%RH, Storage: 35 to 90%RH				
ucture		IP50(IEC Standards)				
Cable		•ENA2				
Cable		•ENA3				
		Ø10mm coupling, Connector cable —				
		CE				
	NPN open - Voltage out PR) <sup>×1</sup> Phase diffe Control output Response time (rise/fall) Max. Resp Power supp Current cor Insulation rn Dielectric si Connection Starting tor Moment of Shaft loadir Max. allowa	NPN open collector output           Voltage output           Voltage output           Phase difference of output           Control output         Totem pole output           Control output         Totem pole output           NPN open collector output         NPN open collector output           Response time (rise/fail)         Totem pole output           NPN open collector output         NPN open collector output           Voltage output         NPN open collector output           Max. Response frequency Power supply         Current consumption Insulation resistance Dielectric strength Connection           Starting torque         Moment of inertia           Shaft loading         Max. allowable revolution <sup>1/2</sup> Ambient temperature Ambient humidity         Ambient humidity	Totem pole output         ENA-□-□-T-□           NPN open collector output         ENA-□-□-N-□           Voltage output         ENA-□-□-N-□           Y1-2: 45, 10, 12, 15, 20, 23, 25, 30, 35, 40, 45, 50, 60, 75, 100, 120, 125, 150, 192, 200, 240, 250, 256, 300, 360, 400, 500, 512, 600, 800, 1000, 1024, 1200, 1500, 1800, 2000, 2008, 2500, 3000, 3600, 5000           PR)*1         Y1-2: 45, 01, 12, 15, 20, 23, 25, 30, 35, 40, 45, 50, 60, 75, 100, 120, 125, 150, 192, 200, 240, 250, 256, 300, 360, 5000           Phase difference of output         Output between A and B phase: 1/4 ± 1/8 (T= 1cycle of A phase)           Phase difference of output         Output between A and B phase: 1/4 ± 1/8 (T= 1cycle of A phase)           Control         Output between A and B phase: 1/4 ± 1/8 (T= 1cycle of A phase)           Phase difference of output         Output between A and B phase: 1/4 ± 1/8 (T= 1cycle of A phase)           Voltage output         Load current: Max. 30mA, Residual voltage: Max. 0.4VDC=::           Control         NPN open collector output           Voltage output         Load current: Max. 10mA, Residual voltage: Max. 0.4VDC=::           Woltage output         Max. 1µs (Cable length:2m, I sink = 20mA)           Voltage output         Max. 1µs (Cable length:2m, I sink = 20mA)           Gurrent consumption         Max. 800 Addisconnection of the load)           Insulation resistance         Min. 100MQ(at 500VDC megger between all terminals and case) <t< td=""></t<>			

%2: Make sure that Max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution

[Max. response revolution(rpm) = <u>Max. response frequency</u> × 60 sec]



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35.7





2m (5m,10m) 43 Ø6























# Connections





-Black: OUT A White: OUT B -Orange: OUT Z -Brown: +V(5VDC, 12-24VDC ±5%) -Blue: GND(0V) Shield: F.G

- \*Unused wires must be insulated.
  \*The metal case and shield cable of encoder should
- be arounded(F.G.). \*Do not apply tensile strength over 30N to the cable.

### ENC Series

#### Axial cable type

- Black: OUT A - White: OUT B - Orange: N.C.(Not connected) - Brown: +V(5VDC, 12-24VDC ±5%) Blue: GND(0V)

- \*Unused wires must be insulated
- %The metal case and shield cable of encoder should be grounded(F.G.).
- %Do not apply tensile strength over 30N to the cable

	Pin No.	Cable color	Function
	1	Black	OUT A
((3 2))	2	White	OUT B
	3	Brown	+V
	4	Blue	GND
(	1	Black	OUT A
	2	White	OUT B
(( ) ( )	3	Orange	OUT Z
	4	Brown	+V
$\bigcirc$	5	Blue	GND

#### Axial cable connector type

Pin No.	Cable color	Function
 1	Black	OUTA
 2	White	OUT B
3	Orange	N.C.
4	Brown	+V
 5	Blue	GND
6	Shield	F.G.

%F.G.(Field Ground) : It should be grounded separately



### Caution during Use

1. Follow instructions in 'Cautions during Use'. Otherwise, It may cause unexpected accidents.

- 2. 5VDC, 12-24VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- 3. For using the unit with the equipment which generates noise (switching regulator, inverter, servo motor, etc.), ground the shield wire to the F.G. terminal.
- . Ground the shield wire to the F.G. terminal.
- 5. When using switching mode power supply, frame ground (F.G.) terminal of power supply should be grounded.
- 6. Wire as short as possible and keep away from high voltage lines or power lines, to prevent inductive noise.
- . Check the wire type and response frequency when extending wire because of distortion of waveform or residual voltage increment etc by line resistance or capacity between lines. 8. This unit may be used in the following environments.
- (Indoors (in the environment condition rated in 'Specifications')

SSRs/Power Controllers

Tachometer/Pulse (Rate) Meters

Counters

Panel Meters

Timers

- ②Altitude max. 2,000m
- ③Pollution degree 2
- ④Installation category II

# Major Products

- Photoelectric Sensors Temperature Controllers Fiber Optic Sensors
- Temperature/Humidity Transducers Door Sensors
- Door Side Sensors
- Area Sensors
- Proximity Sensors
- Pressure Sensors
- Rotary Encoders Display Units
- Connector/Sockets Sensor Controllers
- Switching Mode Power Supplies
- Control Switches/Lamps/Buzzers
- I/O Terminal Blocks & Cables
- Stepper Motors/Drivers/Motion Controllers
- Graphic/Logic Panels
- Field Network Devices
- Laser Marking System (Fiber, CO<sub>2</sub>, Nd: YAG) Laser Welding/Cutting System

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